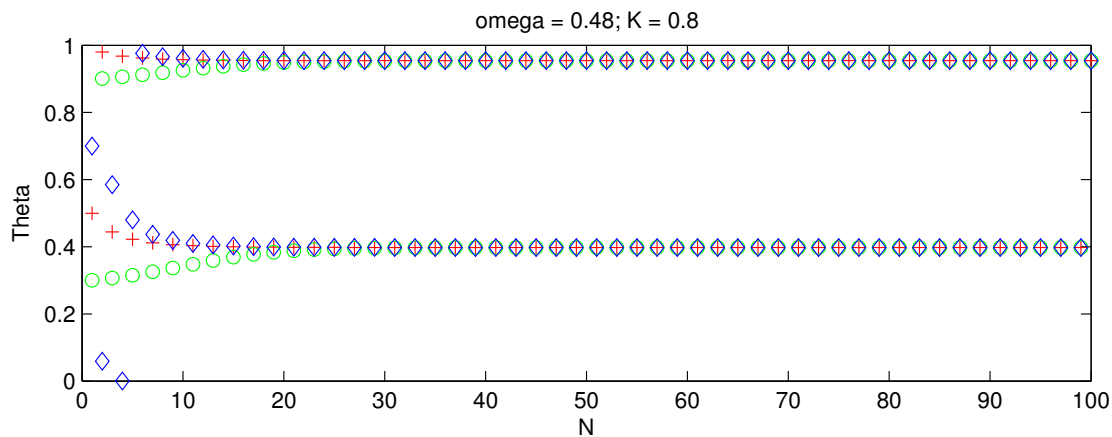
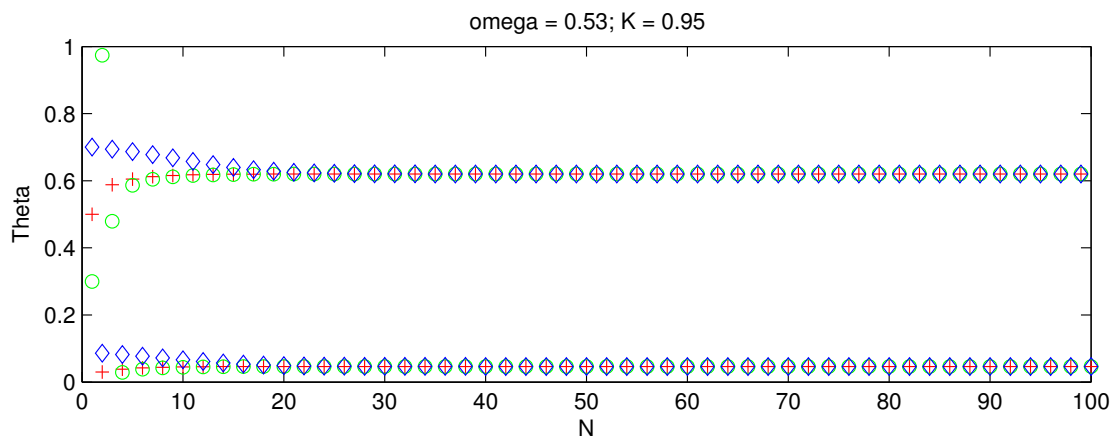
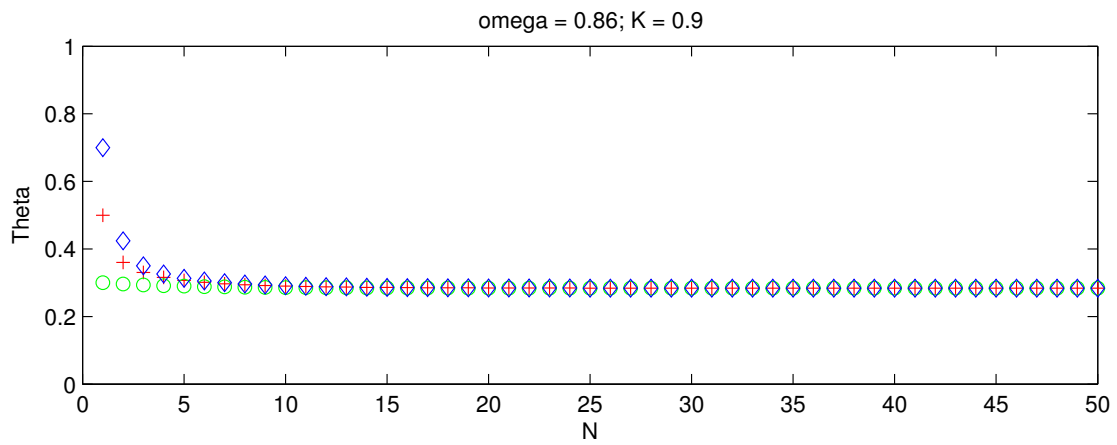
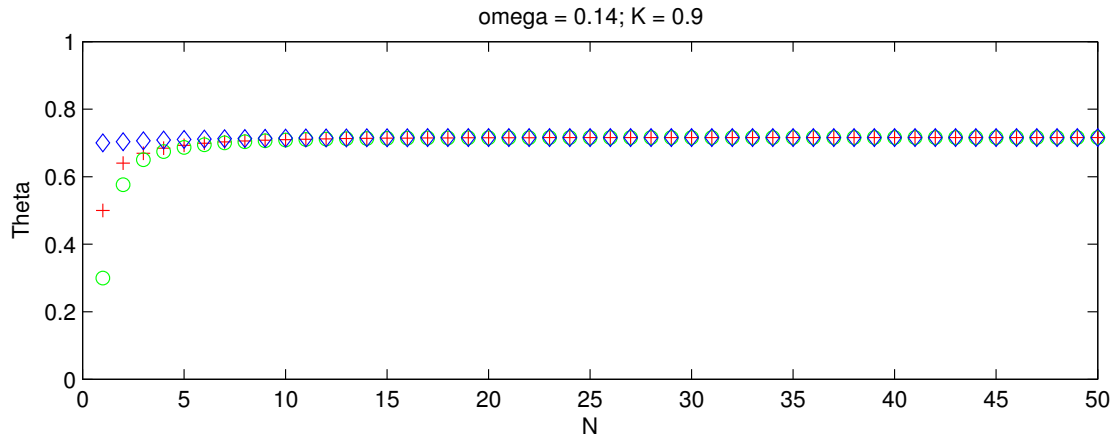


Problem Set 4 Solutions

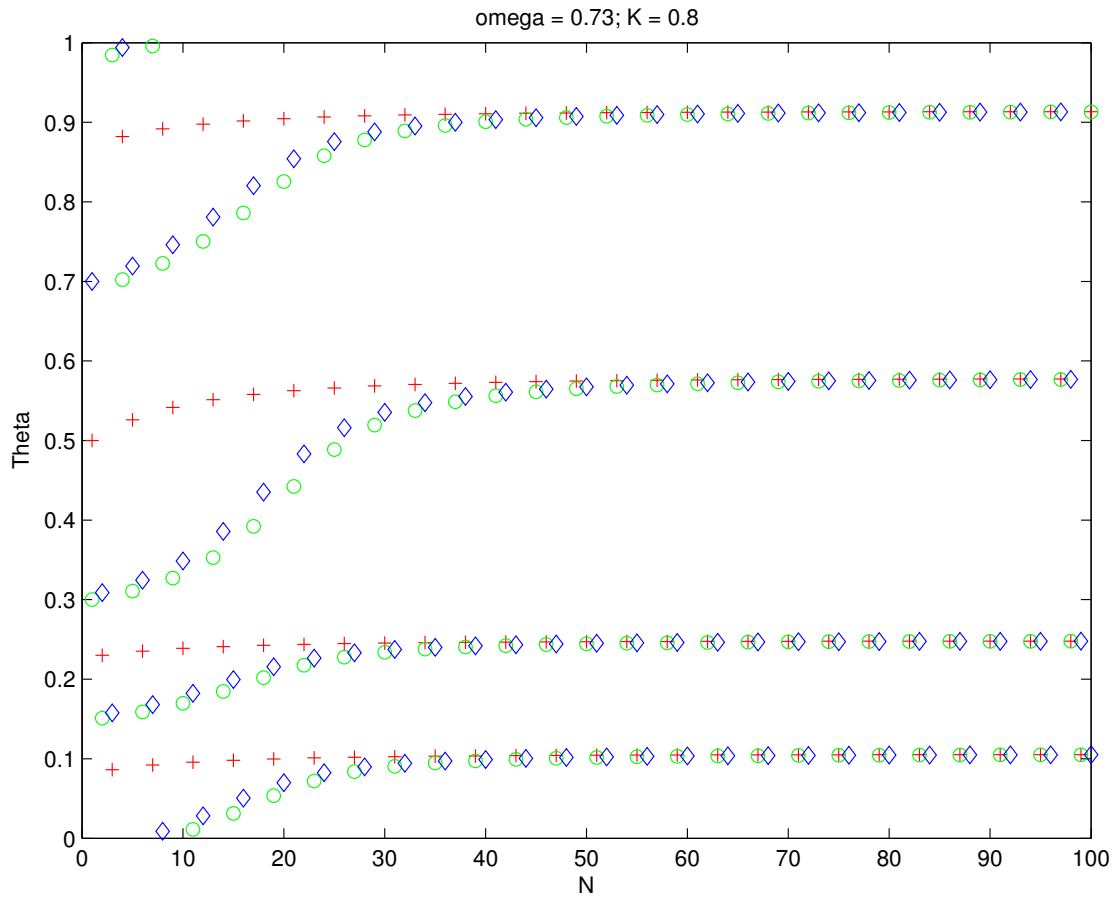
1) a) Here the circle map is integrated at two different K, Ω combinations that both produce $p/q=1/2$ for three initial conditions each.



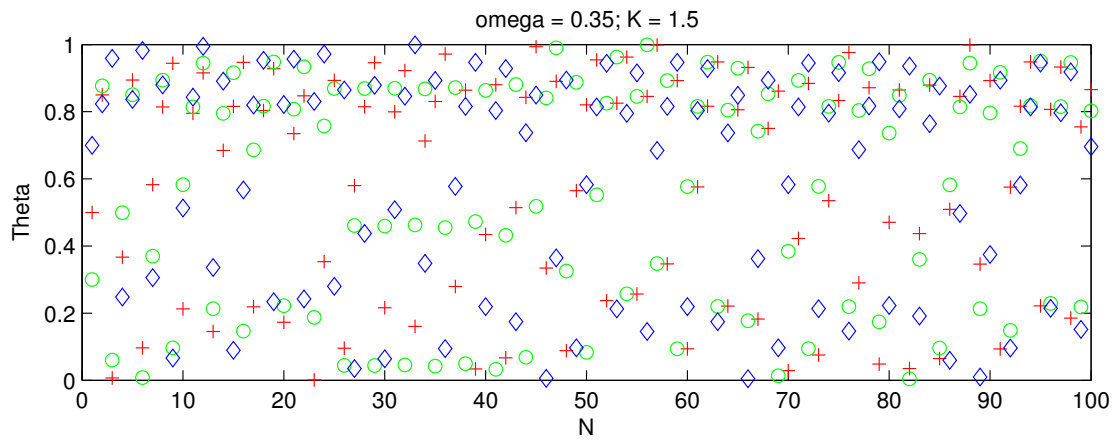
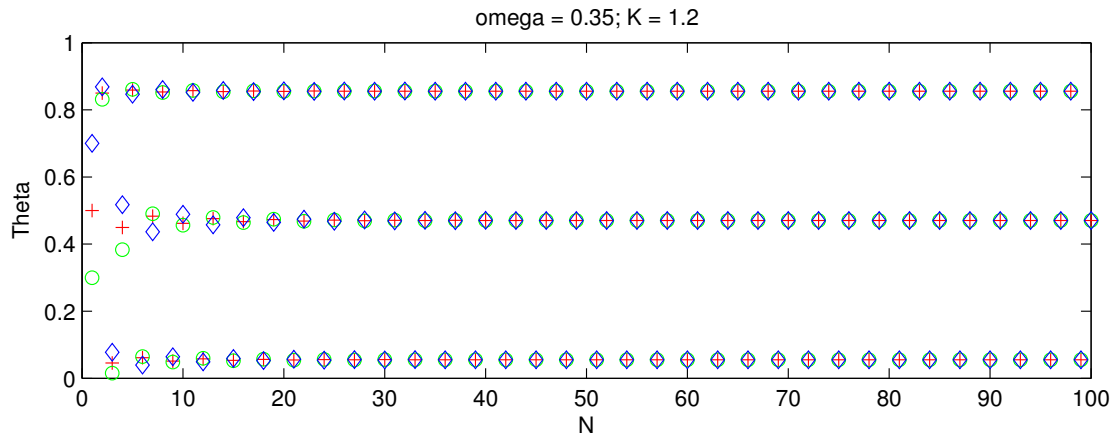
b) The $p/q=0/1$ plot is above and the $p/q=1/1$ plot is below. They look similar - each settles into a period one pattern after some initial behavior.



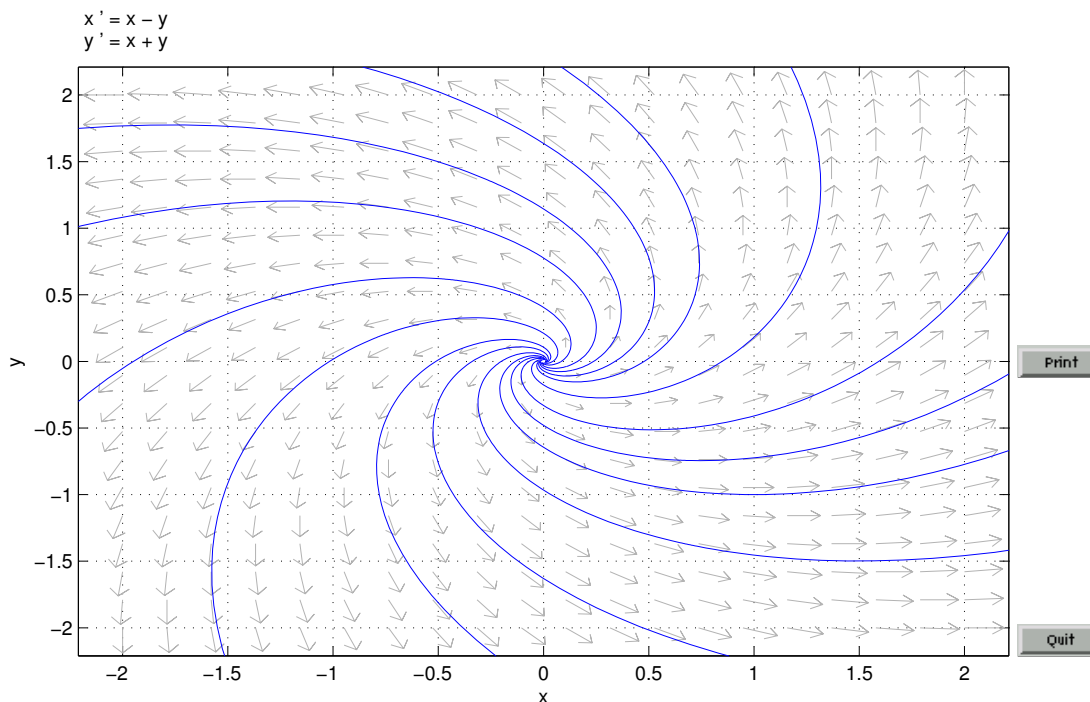
c) A $p/q=3/4$ solution.



d) For $K > 1$ chaotic and nonchaotic regions are densely interwoven in the K - Ω plane.

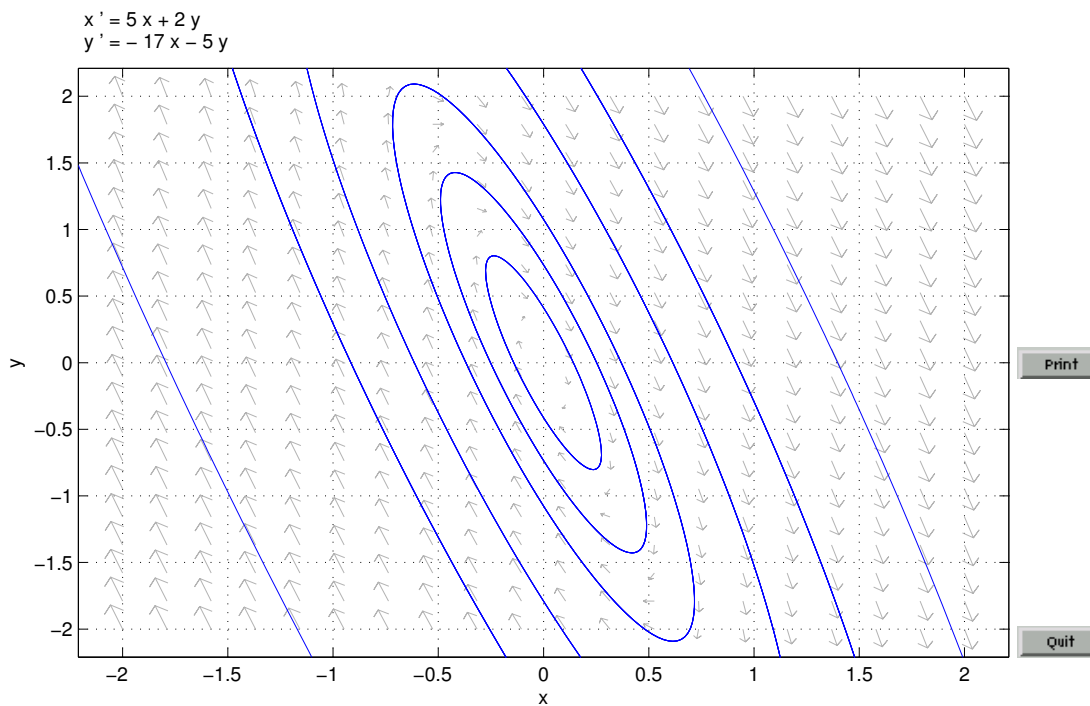


2) a) The f.p. is at $(x,y)=(0,0)$. $A=[1 \ -1; 1 \ 1]$, $\lambda_1=1+i$, $v_1=[1 \ -i]$, $\lambda_2=1-i$, $v_2=[1 \ i]$. An unstable spiral.



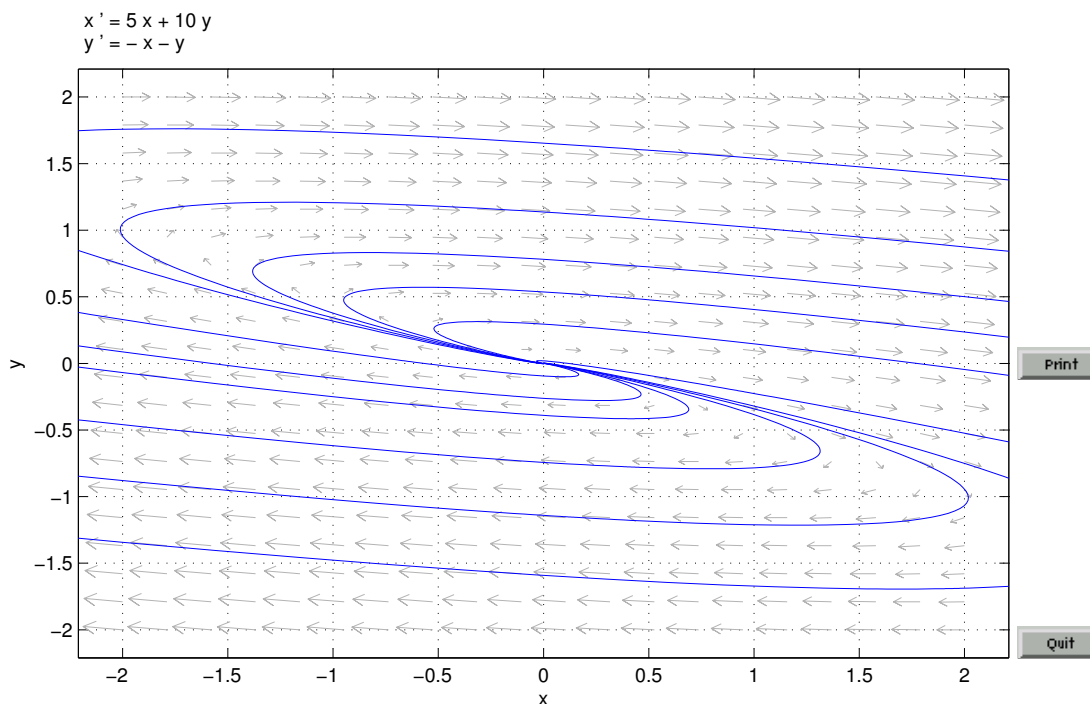
The backward orbit from (0.79, -0.99) --> a possible eq. pt. near (0.0089, 0.007).
 Ready.
 The forward orbit from (0.32, 1.2) left the computation window.
 The backward orbit from (0.32, 1.2) --> a possible eq. pt. near (-0.013, 0.0012).
 Ready.

b) The f.p. is at $(x,y)=(0,0)$. $A=[5 \ 2; -17 \ -5]$, $\lambda_1=3i$, $v_1=[2 \ -5+3i]$, $\lambda_2=-3i$, $v_2=[2 \ -5-3i]$. A center.



The backward orbit from $(0.44, -1.4)$ --> a nearly closed orbit.
 Ready.
 The forward orbit from $(0.92, -1.2)$ --> a nearly closed orbit.
 The backward orbit from $(0.92, -1.2)$ --> a nearly closed orbit.
 Ready.

c) The f.p. is at $(x,y)=(0,0)$. $A=[5 \ 10; -1 \ -1]$, $\lambda_1=2+i$, $v_1=[10 \ -3+i]$, $\lambda_2=2-i$, $v_2=[10 \ -3-i]$. An unstable spiral.

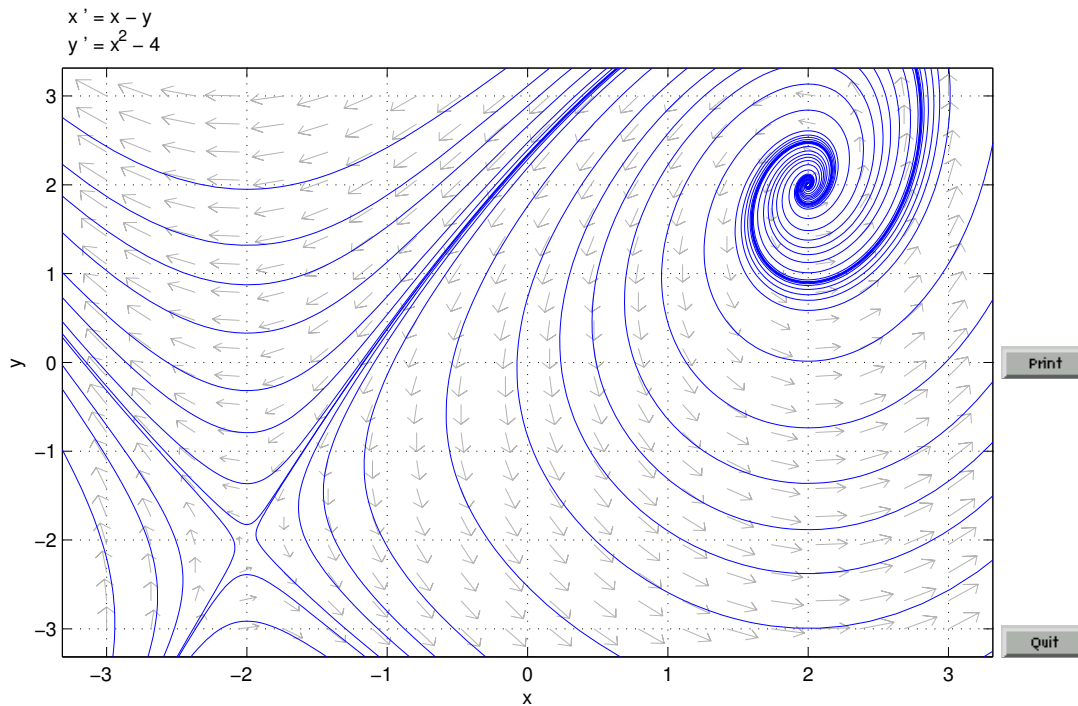


The backward orbit from $(-0.65, 0.018)$ --> a possible eq. pt. near $(0.0031, -0.00046)$.
 Ready.
 The forward orbit from $(0.81, 0.68)$ left the computation window.
 The backward orbit from $(0.81, 0.68)$ --> a possible eq. pt. near $(0.00055, -0.0015)$.
 Ready.

3) a) The f.p. are at $(x,y)=(2,2)$ and $(-2,-2)$. The Jacobian is $J=[1 \ -1; 2x \ 0]$.

$A_1 = J|_{(-2,-2)} = [1 \ -1; -4 \ 0] \Rightarrow \tau = 1, \Delta = -4 \Rightarrow \lambda_1 = \frac{1}{2} + \sqrt{\frac{17}{2}}, v_1 = [2; 1 - \sqrt{17}], \lambda_2 = \frac{1}{2} - \sqrt{\frac{17}{2}}, v_2 = [2; 1 + \sqrt{17}]$. A saddle point.

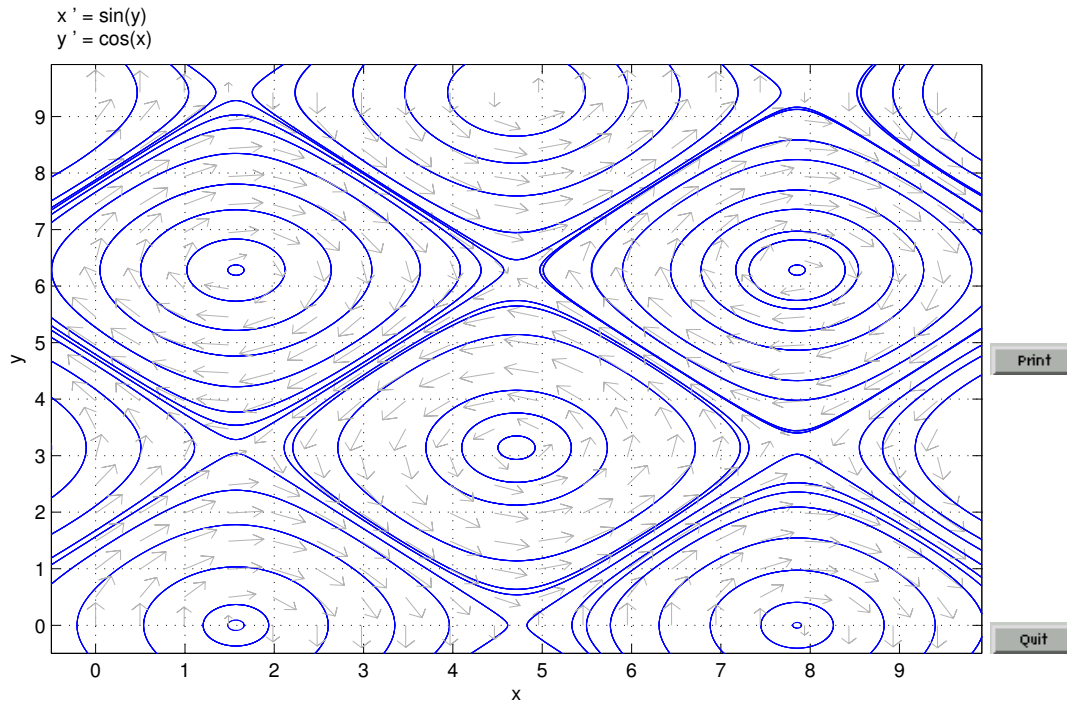
$A_2 = J|_{(2,2)} = [1 \ -1; 4 \ 0] \Rightarrow \tau = 1, \Delta = 4 \Rightarrow \lambda_{1,2} = \frac{1}{2} \pm \frac{\sqrt{15}i}{2}$. An unstable spiral.



The backward orbit from (-3, -2.6) left the computation window.
 Ready.
 The forward orbit from (-2, -1.4) left the computation window.
 The backward orbit from (-2, -1.4) --> a possible eq. pt. near (2, 2).
 Ready.

b) The f.p. are at $(x,y)=((n+\frac{1}{2})\pi,m\pi)$ for integer n and m . The Jacobian is $J=[0 \cos(y); -\sin(y) \ 0]$. $A = J|_{((n+\frac{1}{2})\pi,m\pi)} = [0 \ (-1)^m; (-1)^{n+1} \ 0] \Rightarrow \tau = 0, \Delta = (-1)^{n+m} \Rightarrow \lambda_{1,2} = \pm(-1)^{\frac{n+m+1}{2}}$

For $n+m$ odd, $\lambda_{1,2} = \pm 1$ and we have saddles. For $n+m$ even, $\lambda_{1,2} = \pm i$ and we have centers. We can have centers in this system, even though it is nonlinear, because it is reversible.

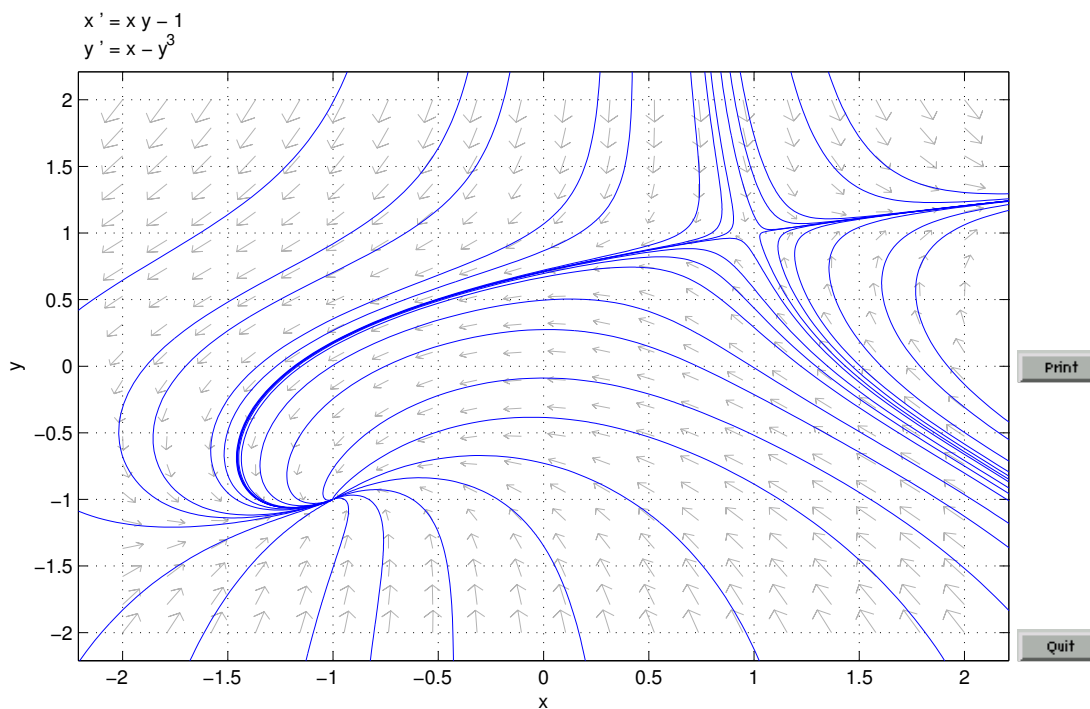


The backward orbit from (8.6, 9) --> a nearly closed orbit.
Ready.
The forward orbit from (8.1, 9) --> a nearly closed orbit.
The backward orbit from (8.1, 9) --> a nearly closed orbit.
Ready.

c) The f.p. are at $(x,y)=(-1,-1)$ and $(1,1)$. The Jacobian is $J=[y \ x; 1 \ -3y^2]$.

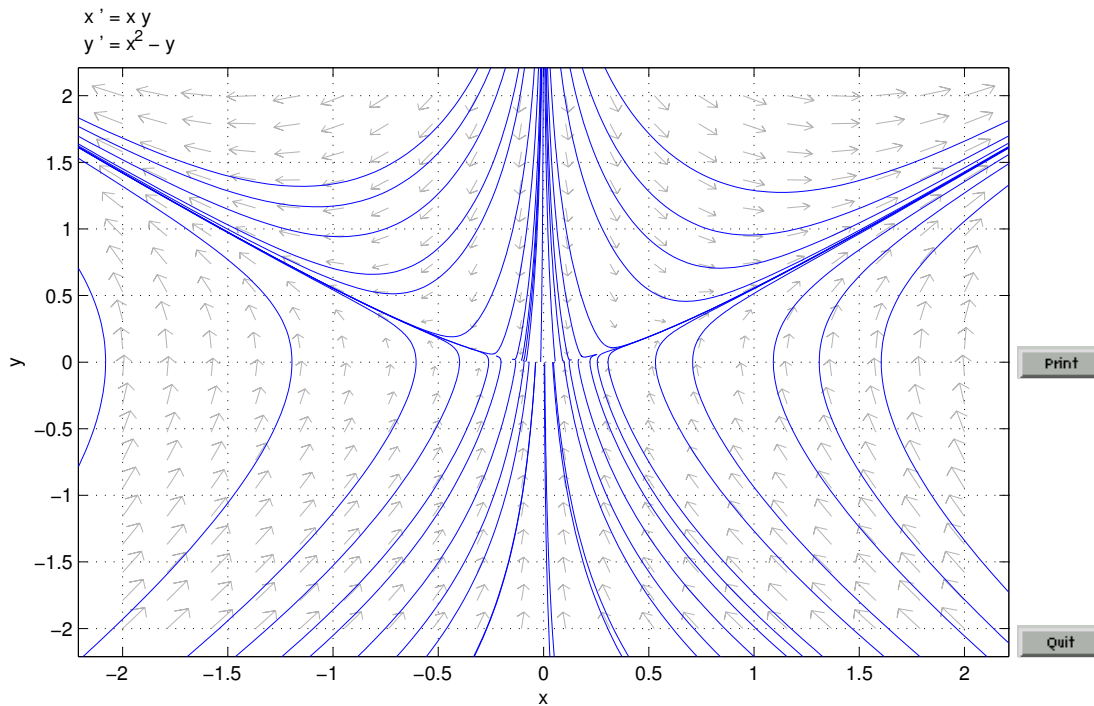
$A_1 = J|_{(-1,-1)} = [-1 \ -1; 1 \ -3] \Rightarrow \tau = -4, \Delta = 4 \Rightarrow \lambda_{1,2} = -2$. In a linear system this could be a star or degenerate node. Since the system is nonlinear, it appears to be a stable node.

$A_2 = J|_{(1,1)} = [1 \ 1; 1 \ -3] \Rightarrow \tau = -2, \Delta = -4 \Rightarrow \lambda_{1,2} = -1 \pm \sqrt{5}$. A saddle point.



The backward orbit from (1.6, 0.59) left the computation window.
 Ready.
 The forward orbit from (1, 0.88) left the computation window.
 The backward orbit from (1, 0.88) left the computation window.
 Ready.

d) The f.p. is at $(x,y)=(0,0)$. The Jacobian is $J=[y \ x; 2x \ -1]$. $A = J|_{(0,0)} = [0 \ 0; 0 \ -1] \Rightarrow \tau = -1, \Delta = 0 \Rightarrow \lambda_{1,2} = 0, -1$. In a linear system this would be a non-isolated f.p. The nonlinear plot looks more like a saddle. Although close to the origin it does look similar to a non-isolated f.p., it in fact isn't. This can be seen by noting that the x and y nullclines intersect only at one point.



The backward orbit from (0.22, -0.39) left the computation window.
 Ready.
 The forward orbit from (0.32, -0.35) left the computation window.
 The backward orbit from (0.32, -0.35) left the computation window.
 Ready.

4) Let's call \bar{F} the circle map with the modulo omitted, that is:

$$\bar{F}(\theta) = \theta + \Omega - \frac{K}{2\pi} \sin(2\pi\theta) \quad (1)$$

Assume that for integers p and q, $\bar{F}^q(\theta) = p + \theta$. The winding number is defined as:

$$w = \lim_{n \rightarrow \infty} \frac{\bar{F}^n(\theta_0) - \theta_0}{n} \quad (2)$$

Let $n=jq+l$, for integers j and l:

$$w = \lim_{j \rightarrow \infty} \frac{\bar{F}^{jq+l}(\theta_0) - \theta_0}{jq+l} \quad (3)$$

Use $\bar{F}^{jq+l}(\theta_0) = \bar{F}^l(jp + \theta_0) \approx jp$ in the limit $j \rightarrow \infty$ (since \bar{F}^l can only add a maximum of l). With this it is clear that:

$$w = \lim_{j \rightarrow \infty} \frac{\bar{F}^{jq+l}(\theta_0) - \theta_0}{jq+l} = \frac{p}{q} \quad (4)$$

The important point here is that we should interpret q as the number of times the function is evaluated before it returns to θ_0 and p as the number of circuits it does as it returns.

For $p=0, q=1$, we have: $\bar{F}(\theta) = \theta \Rightarrow \theta + \Omega - \frac{K}{2\pi} \sin(2\pi\theta) = \theta$. So we have: $\Omega(K) = \frac{K}{2\pi} \sin(2\pi\theta)$. We can only satisfy this relation for any θ for $|\Omega(K)| \leq \frac{K}{2\pi}$ and since $\Omega \in [0, 1]$ the limit of the tongue is given by $\Omega(K) = \frac{K}{2\pi}$.

For $p=1, q=1$, we have: $\bar{F}(\theta) = 1 + \theta \Rightarrow \theta + \Omega - \frac{K}{2\pi} \sin(2\pi\theta) = 1 + \theta$. So we have: $\Omega(K) = 1 + \frac{K}{2\pi} \sin(2\pi\theta)$. We can only satisfy this relation for any θ for $\Omega(K) \geq 1 - \frac{K}{2\pi}$ (and again remember $\Omega \in [0, 1]$), so the limit of the tongue is given by $\Omega(K) = 1 - \frac{K}{2\pi}$.

5) For $p=1, q=2$, we have: $\bar{F}^2(\theta) = 1 + \theta$ or:

$$\left[\theta + \Omega - \frac{K}{2\pi} \sin(2\pi\theta) \right] + \Omega - \frac{K}{2\pi} \sin(2\pi[\theta + \Omega - \frac{K}{2\pi} \sin(2\pi\theta)]) = 1 + \theta \quad (5)$$

We look near $K=0$ and take $\Omega = \frac{1}{2} + \varepsilon$ for small ε , so:

$$\begin{aligned} 2\varepsilon - \frac{K}{2\pi} \sin(2\pi\theta) - \frac{K}{2\pi} \sin\left[2\pi\left(\theta + \frac{1}{2}\right) + 2\pi\varepsilon - K \sin(2\pi\theta)\right] &= 0 \\ 2\varepsilon - \frac{K}{2\pi} \sin(2\pi\theta) + \frac{K}{2\pi} \sin[2\pi\theta + 2\pi\varepsilon - K \sin(2\pi\theta)] &= 0 \\ 2\varepsilon - \frac{K}{2\pi} \sin(2\pi\theta) + \frac{K}{2\pi} \sin(2\pi\theta) + \frac{K}{2\pi} \cos(2\pi\theta)(2\pi\varepsilon - K \sin(2\pi\theta)) &\approx 0 \end{aligned} \quad (6)$$

A Taylor expansion for small K, ε has been used. It is clear from the above equation that $\varepsilon = O(K^2)$, so neglecting ε with respect to K :

$$\begin{aligned} \varepsilon &\approx \frac{K^2}{4\pi} \cos(2\pi\theta) \sin(2\pi\theta) \\ &= \frac{K^2}{8\pi} \sin(4\pi\theta) \end{aligned} \quad (7)$$

$$(8)$$

So the limits of the tongue are $\varepsilon = \pm \frac{K^2}{8\pi}$ or $\Omega = \frac{1}{2} \pm \frac{K^2}{8\pi}$.