

**HARVARD**

**School of Engineering  
and Applied Sciences**

# Pointer Analysis

*CS252r Spring 2011*

# Today: pointer analysis

- What is it? Why? Different dimensions
- Andersen analysis
- Steensgard analysis
- One-level flow
- Pointer analysis for Java

# Pointer analysis

- What memory locations can a pointer expression refer to?
- **Alias analysis:** When do two pointer expressions refer to the same storage location?
- E.g.,  
int x;  
p = &x;  
q = p;
  - \*p and \*q alias,  
as do x and \*p, and x and \*q

# Aliases

- Aliasing can arise due to
  - Pointers
    - e.g., `int *p, i; p = &i;`
  - Call-by-reference
    - `void m(Object a, Object b) { ... }`  
`m(x,x); // a and b alias in body of m`  
`m(x,y); // y and b alias in body of m`
  - Array indexing
    - `int i,j,a[100];`  
`i = j; // a[i] and a[j] alias`

# Why do we want to know?

- Pointer analysis tells us what memory locations code uses or modifies
- Useful in many analyses
- E.g., Available expressions
  - $*p = a + b;$   
 $y = a + b;$
  - If  $*p$  aliases  $a$  or  $b$ , then second computation of  $a+b$  is not redundant
- E.g., Constant propagation
  - $x = 3; *p = 4; y = x;$
  - Is  $y$  constant? If  $*p$  and  $x$  do not alias each other, then yes. If  $*p$  and  $x$  always alias each other, then yes. If  $*p$  and  $x$  sometimes alias each other, then no.

# Some dimensions of pointer analysis

- Intraprocedural / interprocedural
- Flow-sensitive / flow-insensitive
- Context-sensitive / context-insensitive
- Definiteness
  - May versus must
- Heap modeling
- Representation

# Flow-sensitive vs flow-insensitive

- **Flow-sensitive** pointer analysis computes for each program point what memory locations pointer expressions may refer to
- **Flow-insensitive** pointer analysis computes what memory locations pointer expressions may refer to, at any time in program execution
- Flow-sensitive pointer analysis is (traditionally) too expensive to perform for whole program
  - Flow-insensitive pointer analyses typically used for whole program analyses

# Flow-sensitive pointer analysis is hard

Alias Mechanism	Intraprocedural May Alias	Intraprocedural Must Alias	Interprocedural May Alias	Interprocedural Must Alias
Reference Formals, No Pointers, No Structures	–	–	Polynomial[1, 5]	Polynomial[1, 5]
Single level pointers, No Reference Formals, No Structures	Polynomial	Polynomial	Polynomial	Polynomial
Single level pointers, Reference Formals, No Pointer Reference Formals, No Structures	–	–	Polynomial	Polynomial
Multiple level pointers, No Reference Formals, No Structures	$\mathcal{NP}$ -hard	Complement is $\mathcal{NP}$ -hard	$\mathcal{NP}$ -hard	Complement is $\mathcal{NP}$ -hard
Single level pointers, Pointer Reference Formals, No Structures	–	–	$\mathcal{NP}$ -hard	Complement is $\mathcal{NP}$ -hard
Single level pointers, Structures, No Reference Formals	$\mathcal{NP}$ -hard[14]	Complement is $\mathcal{NP}$ -hard	$\mathcal{NP}$ -hard[14]	Complement is $\mathcal{NP}$ -hard

Table 1: Alias problem decomposition and classification

*Pointer-induced Aliasing: A Problem Classification*, Landi and Ryder, POPL 1990

# Context sensitivity

- Also difficult, but success in scaling up to hundreds of thousands LOC
  - BDDs see Whaley and Lam PLDI 2004
  - Doop, Bravenboer and Smaragdakis OOPSLA 2009 (see Thurs)

# Definiteness

- May analysis: aliasing that may occur during execution
  - (cf. **must-not alias**, although often has different representation)
- Must analysis: aliasing that must occur during execution
- Sometimes both are useful
  - E.g., Consider liveness analysis for  $*p = *q + 4$ ;
  - If  $*p$  must alias  $x$ , then  $x$  in kill set for statement
  - If  $*q$  may alias  $y$ , then  $y$  in gen set for statement

# Representation

- Possible representations
  - Points-to pairs: first element points to the second
    - e.g.,  $(p \rightarrow b)$ ,  $(q \rightarrow b)$   
 $*p$  and  $b$  alias, as do  $*q$  and  $b$ , as do  $*p$  and  $*q$
  - Pairs that refer to the same memory
    - e.g.,  $(*p, b)$ ,  $(*q, b)$ ,  $(*p, *q)$ ,  $(**r, b)$
    - General, may be less concise than points-to pairs
  - Equivalence sets: sets that are aliases
    - e.g.,  $\{*p, *q, b\}$

# Modeling memory locations

- We want to describe what memory locations a pointer expression may refer to
- How do we model memory locations?
  - For global variables, no trouble, use a single “node”
  - For local variables, use a single “node” per context
    - i.e., just one node if context insensitive
  - For dynamically allocated memory
    - Problem: Potentially unbounded locations created at runtime
    - Need to model locations with some **finite abstraction**

# Modeling dynamic memory locations

- Common solution:
  - For each allocation statement, use one node per context
  - (Note: could choose context-sensitivity for modeling heap locations to be less precise than context-sensitivity for modeling procedure invocation)
- Other solutions:
  - One node for entire heap
  - One node for each type
  - Nodes based on analysis of “shape” of heap
    - More on this in later lecture

# Problem statement

- Let's consider flow-insensitive may pointer analysis
- Assume program consists of statements of form
  - $p = \&a$  (address of, includes allocation statements)
  - $p = q$
  - $*p = q$
  - $p = *q$
- Assume pointers  $p, q \in P$  and address-taken variables  $a, b \in A$  are disjoint
  - Can transform program to make this true
  - For any variable  $v$  for which this isn't true, add statement  $p_v = \&a_v$ , and replace  $v$  with  $*p_v$
- Want to compute relation  $\text{pts} : P \cup A \rightarrow 2^A$ 
  - Essentially points to pairs

# Andersen-style pointer analysis

- View pointer assignments as **subset constraints**
- Use constraints to propagate points-to information

<b>Constraint type</b>	<b>Assignment</b>	<b>Constraint</b>	<b>Meaning</b>
Base	$a = \&b$	$a \supseteq \{b\}$	$\text{loc}(b) \in \text{pts}(a)$
Simple	$a = b$	$a \supseteq b$	$\text{pts}(a) \supseteq \text{pts}(b)$
Complex	$a = *b$	$a \supseteq *b$	$\forall v \in \text{pts}(b). \text{pts}(a) \supseteq \text{pts}(v)$
Complex	$*a = b$	$*a \supseteq b$	$\forall v \in \text{pts}(a). \text{pts}(v) \supseteq \text{pts}(b)$

# Andersen-style pointer analysis

- Can solve these constraints directly on sets  $\text{pts}(p)$

$p = \&a;$        $p \supseteq \{a\}$

$q = p;$        $q \supseteq p$

$p = \&b;$        $p \supseteq \{b\}$

$r = p;$        $r \supseteq p$

$\text{pts}(p) = \{a, b\}$

$\text{pts}(q) = \{a, b\}$

$\text{pts}(r) = \{a, b\}$

$\text{pts}(a) = \emptyset$

$\text{pts}(b) = \emptyset$

# Another example

```
p = &a  
q = &b  
*p = q;  
r = &c;  
s = p;  
t = *p;  
*s = r;
```

```
p  $\supseteq$  {a}  
q  $\supseteq$  {b}  
*p  $\supseteq$  q  
r  $\supseteq$  {c}  
s  $\supseteq$  p  
t  $\supseteq$  *p  
*s  $\supseteq$  r
```

pts(p) = {a}

pts(q) = {b}

pts(r) = {c}

pts(s) = ~~{a}~~

pts(t) = ~~{b}~~, c}

pts(a) = ~~{b}~~, c}

pts(b) =  $\emptyset$

pts(c) =  $\emptyset$

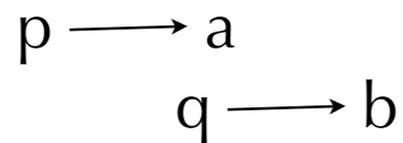
# How precise?

$p = \&a$



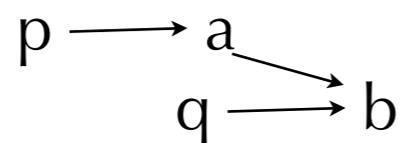
$\text{pts}(p) = \{a\}$

$q = \&b$



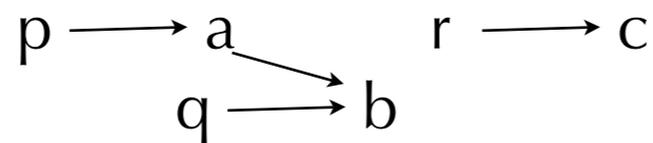
$\text{pts}(q) = \{b\}$

$*p = q;$



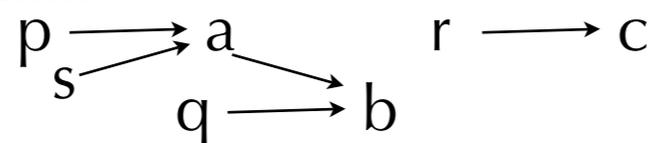
$\text{pts}(r) = \{c\}$

$r = \&c;$



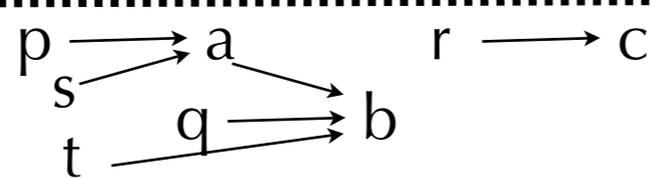
$\text{pts}(s) = \{a\}$

$s = p;$



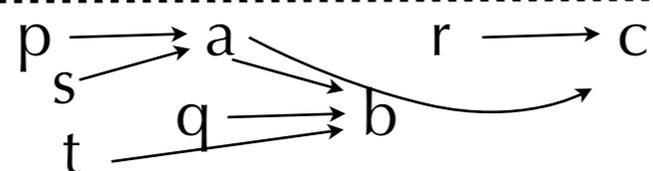
$\text{pts}(t) = \{b,c\}$

$t = *p;$



$\text{pts}(a) = \{b,c\}$

$*s = r;$



$\text{pts}(b) = \emptyset$

$\text{pts}(c) = \emptyset$

# Andersen-style as graph closure

- Can be cast as a graph closure problem
- One node for each  $\text{pts}(p)$ ,  $\text{pts}(a)$

<b>Assgmt.</b>	<b>Constraint</b>	<b>Meaning</b>	<b>Edge</b>
$a = \&b$	$a \supseteq \{b\}$	$b \in \text{pts}(a)$	no edge
$a = b$	$a \supseteq b$	$\text{pts}(a) \supseteq \text{pts}(b)$	$b \rightarrow a$
$a = *b$	$a \supseteq *b$	$\forall v \in \text{pts}(b). \text{pts}(a) \supseteq \text{pts}(v)$	no edge
$*a = b$	$*a \supseteq b$	$\forall v \in \text{pts}(a). \text{pts}(v) \supseteq \text{pts}(b)$	no edge

- Each node has an associated points-to set
- Compute transitive closure of graph, and add edges according to complex constraints

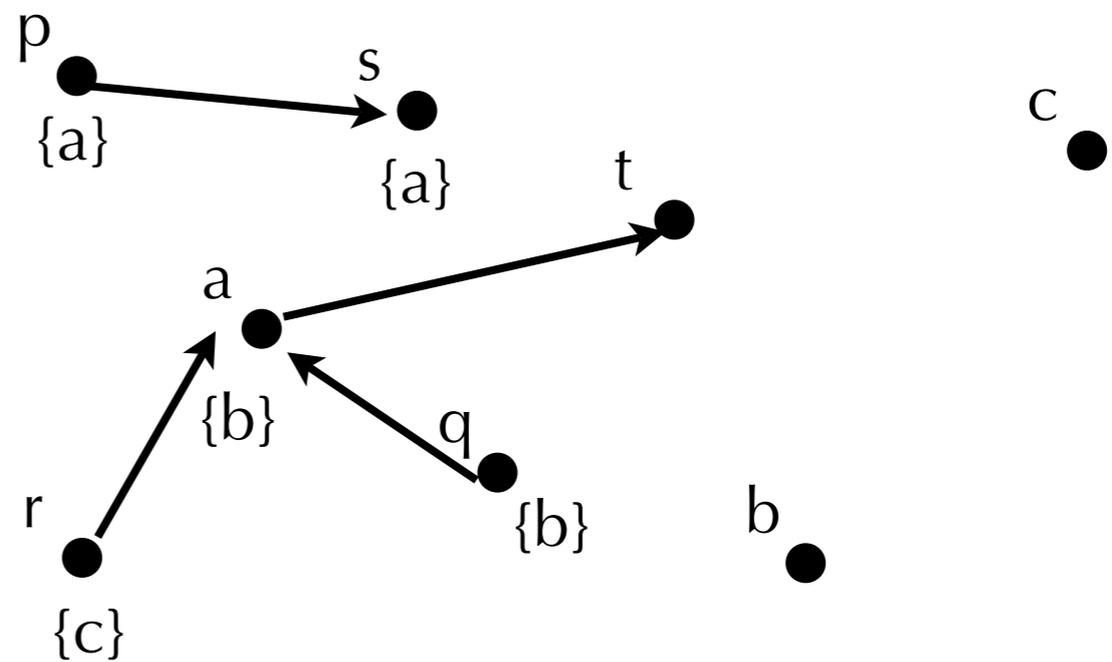
# Workqueue algorithm

- Initialize graph and points to sets using base and simple constraints
- Let  $W = \{ v \mid \text{pts}(v) \neq \emptyset \}$  (all nodes with non-empty points to sets)
- While  $W$  not empty
  - $v \leftarrow$  select from  $W$
  - for each  $a \in \text{pts}(v)$  do
    - for each constraint  $p \supseteq^* v$ 
      - ▶ add edge  $a \rightarrow p$ , and add  $a$  to  $W$  if edge is new
    - for each constraint  $^*v \supseteq q$ 
      - ▶ add edge  $q \rightarrow a$ , and add  $q$  to  $W$  if edge is new
  - for each edge  $v \rightarrow q$  do
    - $\text{pts}(q) = \text{pts}(q) \cup \text{pts}(v)$ , and add  $q$  to  $W$  if  $\text{pts}(q)$  changed

# Same example, as graph

$p = \&a$   
 $q = \&b$   
 $*p = q$   
 $r = \&c$   
 $s = p$   
 $t = *p$   
 $*s = r$

$p \supseteq \{a\}$   
 $q \supseteq \{b\}$   
 $*p \supseteq q$   
 $r \supseteq \{c\}$   
 $s \supseteq p$   
 $t \supseteq *p$   
 $*s \supseteq r$

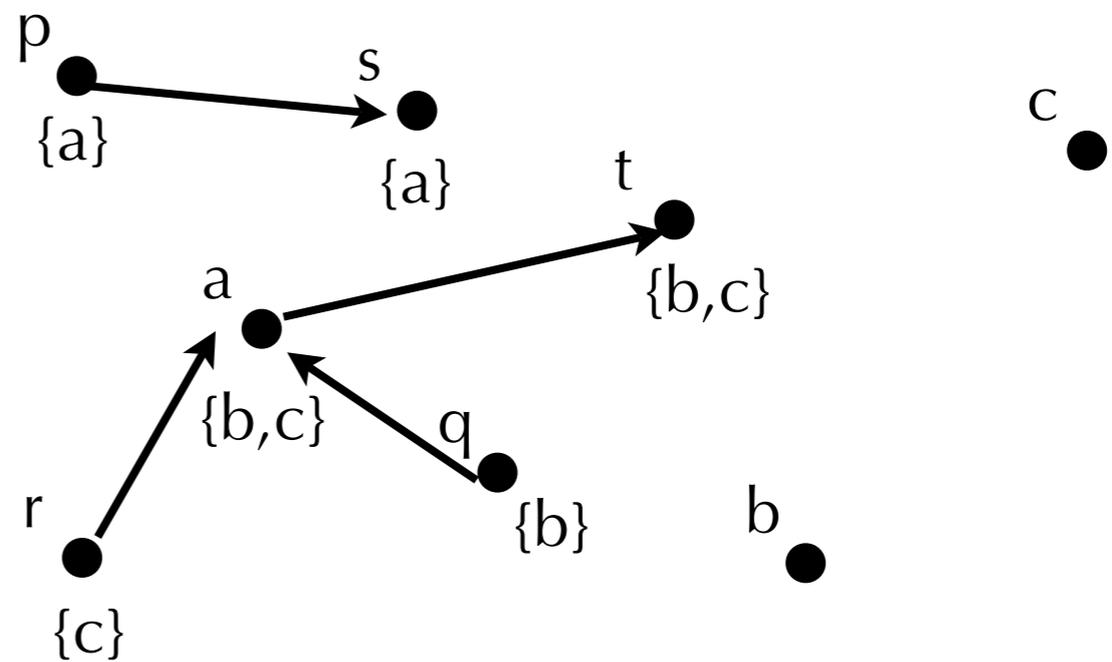


W: p q r s a

# Same example, as graph

$p = \&a$   
 $q = \&b$   
 $*p = q$   
 $r = \&c$   
 $s = p$   
 $t = *p$   
 $*s = r$

$p \supseteq \{a\}$   
 $q \supseteq \{b\}$   
 $*p \supseteq q$   
 $r \supseteq \{c\}$   
 $s \supseteq p$   
 $t \supseteq *p$   
 $*s \supseteq r$



# Cycle elimination

- Andersen-style pointer analysis is  $O(n^3)$ , for number of nodes in graph (Actually, quadratic in practice [Sridharan and Fink, SAS 09])
  - Improve scalability by reducing  $n$
- Cycle elimination
  - Important optimization for Andersen-style analysis
  - Detect strongly connected components in points-to graph, collapse to single node
    - Why? All nodes in an SCC will have same points-to relation at end of analysis
  - How to detect cycles efficiently?
    - Some reduction can be done statically, some on-the-fly as new edges added
    - See *The Ant and the Grasshopper: Fast and Accurate Pointer Analysis for Millions of Lines of Code*, Hardekopf and Lin, PLDI 2007

# Steensgaard-style analysis

- Also a constraint-based analysis
- Uses **equality constraints** instead of subset constraints
  - Originally phrased as a type-inference problem
- Less precise than Andersen-style, thus more scalable

<b>Constraint type</b>	<b>Assignment</b>	<b>Constraint</b>	<b>Meaning</b>
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Complex	$*a = b$	$*a = b$	$\forall v \in \text{pts}(a). \text{pts}(v) = \text{pts}(b)$

# Implementing Steensgaard-style analysis

- Can be efficiently implemented using Union-Find algorithm
  - Nearly linear time:  $O(n\alpha(n))$
  - Each statement needs to be processed just once

# One-level flow

- *Unification-based Pointer Analysis with Directional Assignment*, Das, PLDI 2000
- Observation: common use of pointers in C programs is to pass the address of composite objects or updateable arguments; multi-level use of pointers not as common
- Uses unification (like Steensgaard) but avoids unification of **top-level pointers** (pointers that are not themselves pointed to by other pointers)
  - i.e., Use Andersen's rules at top level, Steensgaard's elsewhere

# One-level flow

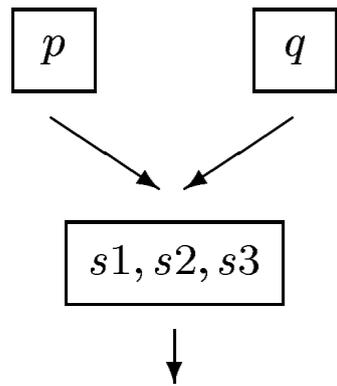
```
foo(&s1);  
foo(&s2);  
bar(&s3);
```

```
foo(struct s *p) { *p.a = 3; bar(p); }  
bar(struct s *q) { *q.b = 4; }
```

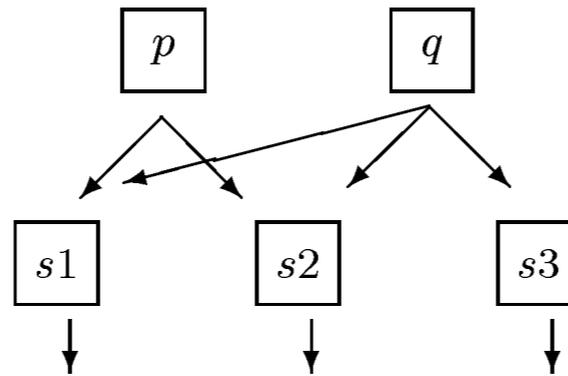
```
p = &s1;  
p = &s2;  
q = &s3;  
q = p;  
*p.a = 3;  
*q.b = 4;
```

(a)

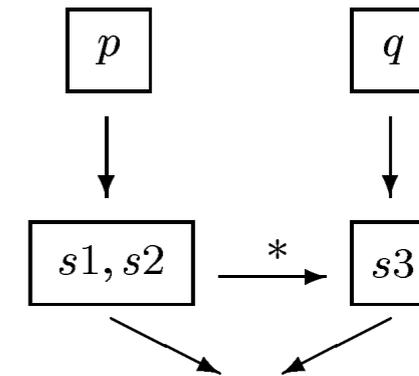
(b)



(c)



(d)



(e)

Figure 1: Two programs that illustrate the difference between the algorithms of Steensgaard and Andersen. The program in (a) above represents the common case in C programs, while the program in (b) above is a variant of the program without procedure calls. Figures (c), (d) and (e) above show the points-to graphs computed by Steensgaard's algorithm, Andersen's algorithm, and our one level flow algorithm, respectively, for the program in (b) above. The edge labeled with \* is a flow edge.

- Precision close to Andersen's, scalability close to Steensgaard's
  - At least, for programs where observation holds.
- Doesn't hold in Java, C++, ...

# Pointer analysis in Java

- Different languages use pointers differently
- *Scaling Java Points-To Analysis Using SPARK* Lhotak & Hendren CC 2003
  - Most C programs have many more occurrences of the address-of (&) operator than dynamic allocation
    - & creates stack-directed pointers; malloc creates heap-directed pointers
  - Java allows no stack-directed pointers, many more dynamic allocation sites than similar-sized C programs
  - Java strongly typed, limits set of objects a pointer can point to
    - Can improve precision
  - Call graph in Java depends on pointer analysis, and vice-versa (in context sensitive pointer analysis)
  - Dereference in Java only through field store and load
  - And more...
    - Larger libraries in Java, more entry points in Java, can't alias fields in Java, ...

# Object-sensitive pointer analysis

- Milanova, Rountev, and Ryder. *Parameterized object sensitivity for points-to analysis for Java*. ACM Trans. Softw. Eng. Methodol., 2005.
  - Context-sensitive interprocedural pointer analysis
  - For context, use stack of receiver objects
  - (More next week?)
- Lhotak and Hendren. *Context-sensitive points-to analysis: is it worth it?* CC 06
  - Object-sensitive pointer analysis more precise than call-stack contexts for Java
  - Likely to scale better

# Closing remarks

- Pointer analysis: important, challenging, active area
  - Many clients, including call-graph construction, live-variable analysis, constant propagation, ...
  - Inclusion-based analyses (aka Andersen-style)
  - Equality-based analyses (aka Steensgaard-style)
- Requires a tradeoff between precision and efficiency
  - Ultimately an empirical question. Which clients, which code bases?
- Recent results promising
  - Scalable flow-sensitivity (see Thurs, and Hardekopf and Lin, POPL 09)
  - Context-sensitive Andersen-style analyses seem scalable (See Thurs)
- Other issues/questions (see Hind, PASTE'01)
  - How to measure/compare pointer analyses? Different clients have different needs
  - Demand-driven analyses? May be more precise/scalable...